LEGISLATURE OF NEBRASKA ONE HUNDRED SIXTH LEGISLATURE FIRST SESSION

LEGISLATIVE BILL 521

Introduced by McDonnell, 5. Read first time January 22, 2019 Committee:

A BILL FOR AN ACT relating to motor vehicles; to amend sections 60-3301,
60-3302, 60-3303, 60-3304, and 60-3308, Revised Statutes Cumulative
Supplement, 2018; to change and eliminate provisions relating to
automated vehicles; to repeal the original sections; and to outright
repeal section 60-3306, Revised Statutes Cumulative Supplement,
2018.
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7 Be it enacted by the people of the State of Nebraska,

Section 1. Section 60-3301, Revised Statutes Cumulative Supplement,
 2018, is amended to read:

3 60-3301 For purposes of sections 60-3301 to 60-3311, the following4 definitions apply:

5 (1) Automated driving system means the hardware and software that 6 are collectively capable of performing the entire dynamic driving task on 7 a sustained basis regardless of whether it is limited to a specific 8 operational design domain, if any;

9 (2) Automated-driving-system-equipped vehicle means a motor vehicle
10 equipped with an automated driving system;

(3) Conventional human driver means a human person who manually
 exercises in-vehicle braking, accelerating, steering, and transmission
 gear selection input devices in order to operate a motor vehicle;

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(4) Department means the Department of Motor Vehicles;

(5) Driverless-capable vehicle means a motor vehicle equipped with an automated driving system capable of performing all aspects of the dynamic driving task within its operational design domain, if any, including achieving a minimal risk condition, without any intervention or supervision by a conventional human driver, so long as a conventional human driver is physically present in the vehicle and able to take control of the vehicle;

(6) Dynamic driving task means all of the real-time operational and
tactical functions required to operate a motor vehicle within its
specific operational design domain, if any, excluding the strategic
functions such as trip scheduling and selection of destinations and
waypoints;

(7) Minimal risk condition means a reasonably safe state to which an automated driving system brings an automated-driving-system-equipped vehicle upon experiencing a performance-related failure of the vehicle's automated driving system that renders the vehicle unable to perform the entire dynamic driving task, such as bringing the vehicle to a complete

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1 stop and activating the hazard lamps;

2 (8) On-demand driverless-capable vehicle network means а transportation service network that uses a software application or other 3 4 digital means to dispatch driverless-capable vehicles for purposes of 5 transporting persons or goods, including for-hire transportation, transportation for compensation, and public transportation, and is in 6 7 compliance with all applicable state and federal labor laws; and

8 (9) Operational design domain means a description of the specific 9 operating domain in which an automated driving system is designed to 10 properly operate, including, but not limited to, roadway types, speed 11 range, environmental conditions such as weather and time of day, and 12 other domain constraints; and \pm

(10) School crossing zone has the same meaning as in section
 60-658.01.

Sec. 2. Section 60-3302, Revised Statutes Cumulative Supplement,
2018, is amended to read:

60-3302 A driverless-capable vehicle may operate on the public roads
of this state <u>with</u> without a conventional human driver physically present
in the vehicle, as long as the vehicle meets the following conditions:

(1) The vehicle is capable of achieving a minimal risk condition if
a malfunction of the automated driving system occurs that renders the
system unable to perform the entire dynamic driving task within its
intended operational design domain, if any; and

24 (2) While in driverless operation, the vehicle is capable of 25 operating in compliance with the applicable traffic and motor vehicle safety laws and regulations of this state that govern the performance of 26 27 the dynamic driving task, including, but not limited to, safely 28 negotiating railroad crossings and school crossing zones, unless an exemption has been granted by the department. The department shall 29 consult with the railroad companies operating in this state and local law 30 31 enforcement agencies when considering an exemption that affects vehicle

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Sec. 3. Section 60-3303, Revised Statutes Cumulative Supplement,
2018, is amended to read:

4 60-3303 (1) Notwithstanding any other provision of law, the 5 operation on the public roads of this state of an automated-drivingsystem-equipped vehicle capable of performing the entire dynamic driving 6 7 task within its operational design domain while a conventional human driver is physically present in the vehicle is lawful. Such operation 8 9 shall be subject to the Nebraska Rules of the Road, as applicable. In addition, the conventional human driver shall be licensed as required 10 under the Motor Vehicle Operator's License Act, shall remain subject to 11 the Nebraska Rules of the Road, shall operate the automated-driving-12 13 system-equipped vehicle according to the manufacturer's requirements and specifications, and shall regain manual control of the vehicle upon the 14 request of the automated driving system. 15

(2) The automated driving system feature, while engaged, shall be 16 17 designed to operate within its operational design domain in compliance with the Nebraska Rules of the Road, including, but not limited to, 18 safely negotiating railroad crossings and school crossing zones, unless 19 an exemption has been granted by the department. The department shall 20 consult with the railroad companies operating in this state when 21 22 considering an exemption that affects vehicle operations at railroad 23 crossings.

24 Sec. 4. Section 60-3304, Revised Statutes Cumulative Supplement, 25 2018, is amended to read:

60-3304 Before an automated-driving-system-equipped vehicle <u>or a</u> <u>driverless-capable vehicle</u> may operate on the public roads of this state, a person shall submit proof of financial responsibility satisfactory to the department that the automated-driving-system-equipped vehicle <u>or a</u> <u>driverless-capable vehicle</u> is covered by insurance or proof of selfinsurance that satisfies the requirements of the Motor Vehicle Safety

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1 Responsibility Act.

Sec. 5. Section 60-3308, Revised Statutes Cumulative Supplement,
2018, is amended to read:

60-3308 (1) Automated-driving-system-equipped vehicles, driverless<u>capable vehicles</u>, and automated driving systems, and on-demand
<u>driverless-vehicle networks</u> are governed exclusively by sections 60-3301
to 60-3311. The department <u>shall</u> is the sole and exclusive state agency
<u>that may</u> implement sections 60-3301 to 60-3311.

9 (2) The state or any political subdivision shall not impose 10 requirements, including performance standards, specific to the operation 11 of automated-driving-system-equipped vehicles, automated driving systems, 12 or on-demand driverless-capable vehicle networks in addition to the 13 requirements of sections 60-3301 to 60-3311.

14 (3) The state or any political subdivision thereof shall not impose 15 a tax or other requirements on an automated-driving-system-equipped 16 vehicle, an automated driving system, or an on-demand driverless-capable 17 vehicle network, where such tax or other requirements relate specifically 18 to the operation of automated-driving-system-equipped vehicles.

Sec. 6. Original sections 60-3301, 60-3302, 60-3303, 60-3304, and
 60-3308, Revised Statutes Cumulative Supplement, 2018, are repealed.

21 Sec. 7. The following section is outright repealed: Section 22 60-3306, Revised Statutes Cumulative Supplement, 2018.

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