

1 SB47
2 200574-8
3 By Senator Allen
4 RFD: Transportation and Energy
5 First Read: 05-MAR-19
6 PFD: 03/04/2019

1 SB47

2
3
4 ENROLLED, An Act,

5 Relating to motor vehicles; to authorize autonomous
6 commercial vehicles operated by an automated driving system
7 and commercial motor vehicles with teleoperation systems.

8 BE IT ENACTED BY THE LEGISLATURE OF ALABAMA:

9 Section 1. For the purposes of this act, the
10 following words shall have the following meanings:

11 (1) AUTOMATED COMMERCIAL MOTOR VEHICLE. A commercial
12 motor vehicle equipped with an automated driving system.

13 (2) AUTOMATED DRIVING SYSTEM. The hardware and
14 software that are collectively capable of performing the
15 entire dynamic driving task on a sustained basis, regardless
16 of whether it is limited to a specific operational design
17 domain.

18 (3) COMMERCIAL MOTOR VEHICLE. A commercial motor
19 vehicle as defined in subdivision (2) of Section 32-9A-1, Code
20 of Alabama 1975.

21 (4) CONVENTIONAL DRIVER. A driver who manually
22 exercises in-vehicle braking, accelerating, steering, and
23 transmission gear selection input devices in order to operate
24 a vehicle.

1 (5) DYNAMIC DRIVING TASK. All of the real-time
2 operational and tactical functions required to operate a
3 vehicle in on-road traffic excluding strategic functions such
4 as trip scheduling and selection of destinations and
5 waypoints.

6 (6) MINIMAL RISK CONDITION. A condition to which a
7 user or an automated driving system may bring a vehicle in
8 order to reduce the risk of a crash upon experiencing a
9 failure of the vehicle's automated driving system that renders
10 the vehicle unable to perform the entire dynamic driving task.

11 (7) OPERATIONAL DESIGN DOMAIN. A description of the
12 specific operating domain in which an automated commercial
13 motor vehicle is designed to properly operate, including, but
14 not limited to, roadway types, speed, environmental
15 conditions, and other domain constraints.

16 (8) REMOTE DRIVER. A natural person who is not
17 seated in a commercial motor vehicle, but is able to perform
18 the entire dynamic driving task.

19 (9) TELEOPERATION SYSTEM. Hardware and software
20 installed on a commercial motor vehicle that allow a remote
21 driver to operate the motor vehicle.

22 Section 2. (a) Unless otherwise provided by this
23 act, an automated commercial motor vehicle and a teleoperation
24 system, including any commercial use or operation of either,
25 are governed exclusively by this act.

1 (b) Notwithstanding any other provision of law, the
2 Department of Transportation is the sole and exclusive state
3 agency with jurisdiction over automated commercial motor
4 vehicles and teleoperation systems that may implement this
5 act.

6 (c) A political subdivision of this state or a state
7 agency may not impose requirements, including taxes or
8 performance standards, related specifically to the operation
9 of a teleoperation system or automated commercial motor
10 vehicle in addition to the requirements of this act.

11 Section 3. Notwithstanding any other provision of
12 law, an automated commercial motor vehicle may operate in this
13 state without a conventional driver physically present in the
14 vehicle if the vehicle meets all of the following criteria:

15 (1) The automated commercial vehicle is capable of
16 operating in compliance with applicable federal law and the
17 traffic and motor vehicle laws of this state, including
18 without limitation, applicable laws concerning the capability
19 to safely navigate and negotiate railroad crossings.

20 (2) The automated commercial vehicle is registered
21 and titled in accordance with the laws of this state.

22 (3) The automated commercial vehicle is certified in
23 accordance with 49 C.F.R. Part 567 as being in compliance with
24 federal motor vehicle safety standards and bears the required

1 certification label or labels, including reference to any
2 exemption granted under applicable federal law.

3 (4) The automated commercial vehicle can achieve a
4 minimal risk condition if a failure occurs rendering the
5 vehicle unable to perform the dynamic driving task relevant to
6 its intended operational design domain or if the vehicle exits
7 its operational design domain.

8 (5) The automated commercial vehicle is covered by
9 motor vehicle liability coverage in an amount not less than
10 two million dollars (\$2,000,000).

11 (6) The registration of an automated commercial
12 motor vehicle shall not be interpreted to abrogate or amend
13 any statutory or regulatory provisions or any aspects of
14 common law pertaining to liability for any harm or injury
15 caused.

16 Section 4. (a) The owner of an automated commercial
17 vehicle, or the lessee if the vehicle is leased or rented, is
18 considered the operator of the vehicle for the purpose of
19 assessing compliance with applicable traffic or motor vehicle
20 laws, including the rules of the road.

21 (b) The automated driving system is considered to be
22 licensed to operate the vehicle.

23 Section 5. When an accident occurs involving an
24 automated commercial motor vehicle, the requirements of
25 Chapter 10, Title 32, Code of Alabama 1975, shall be deemed

1 satisfied if the vehicle remains on the scene of the accident
2 and the vehicle, owner, a person on behalf of the owner, or
3 operator promptly contacts appropriate law enforcement
4 entities and communicates the information required by Chapter
5 10, Title 32, Code of Alabama 1975.

6 Section 6. (a) Notwithstanding any other provision
7 of this act, a commercial motor vehicle equipped with a
8 teleoperation system may operate without a conventional driver
9 physically present in the vehicle if a remote driver is
10 operating the vehicle.

11 (b) When a remote driver is operating a commercial
12 motor vehicle, the remote driver is considered to be the
13 operator of the vehicle for the purpose of assessing
14 compliance with applicable traffic or motor vehicle laws,
15 including the rules of the road, and for the purpose of any
16 charge for a violation of the Alabama Criminal Code, Title
17 13A, Code of Alabama 1975, or Title 32, Code of Alabama 1975.
18 Extradition of a person charged pursuant to this section shall
19 be governed by Chapter 9 of Title 15, Code of Alabama 1975.

20 (c) The remote driver shall hold the proper class of
21 license required for a conventional driver to operate the
22 vehicle.

23 (d) When an accident occurs involving a commercial
24 motor vehicle equipped with a teleoperation system, the
25 requirements of Chapter 10, Title 32, Code of Alabama 1975,

1 shall be deemed satisfied if the vehicle remains on the scene
2 of the accident and the owner or remote driver promptly
3 contacts appropriate law enforcement entities and communicates
4 the information required by Chapter 10, Title 32, Code of
5 Alabama 1975.

6 (e) In the event of an accident involving a
7 commercial motor vehicle equipped with a teleoperation system,
8 the remote driver who is operating the vehicle shall be subject
9 to Section 32-6-49.13, Code of Alabama 1975, regardless of the
10 jurisdiction in which the remote driver is physically present.
11 A remote driver is deemed to have give consent, subject to
12 provisions of Section 32-5-192, Code of Alabama 1975, to take
13 a test or tests of the remote driver's blood, breath, or urine
14 for the purpose of determining that the person's alcohol
15 concentration, or the presence of other drugs. Subdivision (1)
16 of subsection (b) of Section 32-6-49.13 shall be deemed
17 satisfied if the test or tests are administered in cooperation
18 with local law enforcement officials in the jurisdiction where
19 a remote driver is present. The results of any test shall be
20 provided to Alabama law enforcement agencies.

21 Section 7. A commercial motor vehicle equipped with
22 a teleoperation system registered in this state shall meet all
23 of the following requirements:

24 (1) The motor vehicle shall be in compliance with
25 applicable federal law.

1 (2) The motor vehicle shall be certified in
2 accordance with federal regulations in 49 C.F.R. Part 567 as
3 being in compliance with applicable federal motor vehicle
4 safety standards and shall bear the required certification
5 label or labels, including reference to any exemption granted
6 under applicable federal law.

7 (3) The motor vehicle shall be capable of being
8 operated in compliance with the applicable traffic and motor
9 vehicle laws of this state, regardless of whether the vehicle
10 is operated by a remote driver, including without limitation,
11 applicable laws concerning the capability to safely navigate
12 and negotiate railroad crossings.

13 (4) The motor vehicle shall be covered by motor
14 vehicle liability coverage in an amount of not less than two
15 million dollars (\$2,000,000).

16 (5) The motor vehicle shall be able to achieve a
17 reasonably safe state, such as bringing the vehicle to a stop,
18 if a failure of the teleoperation system occurs that renders
19 the remote driver unable to perform the entire dynamic driving
20 task for the vehicle.

21 Section 8. This act shall not be construed to
22 repeal, modify, or preempt any liability that may be incurred
23 under existing common or statutory law applicable to a vehicle
24 owner, operator, manufacturer, component part supplier, or
25 retailer.

1 Section 9. This act shall become effective
2 immediately following its passage and approval by the
3 Governor, or its otherwise becoming law.

1
2
3
4
5
6
7
8
9
10
11
12
13
14
15
16
17
18
19
20
21
22
23
24

President and Presiding Officer of the Senate

Speaker of the House of Representatives

SB47

Senate 21-MAY-19

I hereby certify that the within Act originated in and passed the Senate, as amended.

Patrick Harris,
Secretary.

House of Representatives
Amended and passed 28-MAY-19

Senate concurred in House amendment 29-MAY-19

By: Senator Allen